

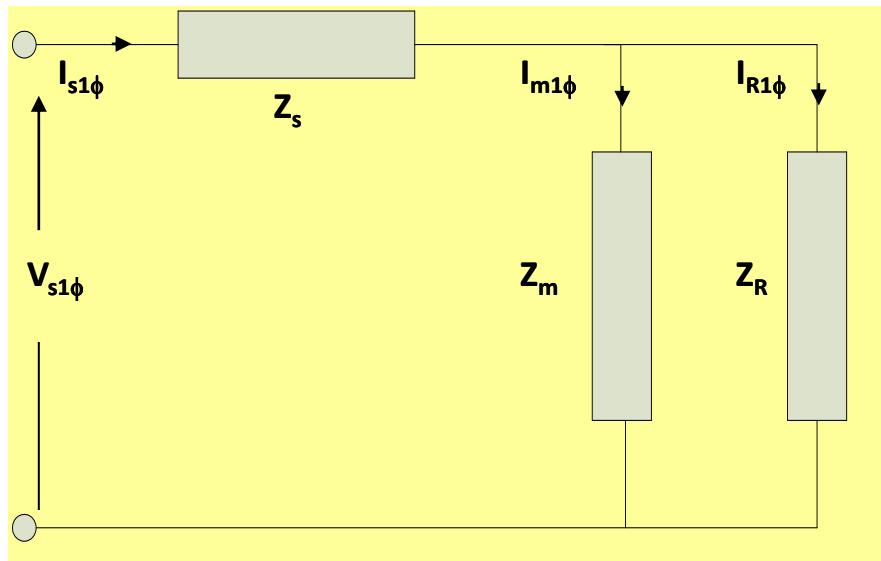
- LECTURE 3

Analysis of Induction Machines

- For simplicity, let assume

$$I_s = I_1, \quad I_R = I_2$$

(s=stator, R=rotor)



$$Z_R = \frac{R_R'}{s} + jX_R' \quad ;$$

$$Z_m = R_c // jX_m \quad ; R_c \neq \text{neglected}$$

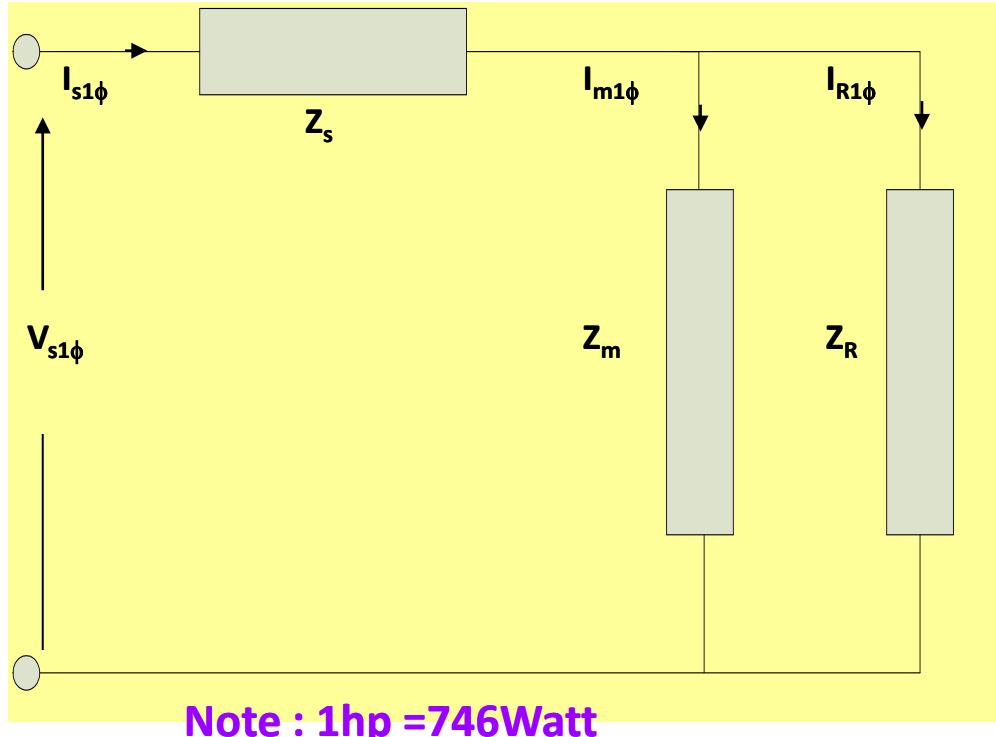
$$Z_m = jX_m \quad ; R_c = \text{neglected}$$

$$Z_s = R_s + jX_s \quad ;$$

$$Z_{Total} = Z_s + [Z_m // Z_R]$$

$$I_{s1\phi} = \frac{V_{s1\phi}}{Z_T}$$

Analysis of Induction Machines



Current Dividing Rules ,

$$I_{m1\phi} = \left[\frac{Z_R}{Z_m + Z_R} \right] I_{s1\phi}$$

$$I_{R1\phi} = \left[\frac{Z_m}{Z_m + Z_R} \right] I_{s1\phi}$$

OR

Voltage Dividing Rules ,

$$V_{RM1\phi} = \left[\frac{Z_R // Z_m}{Z_T} \right] V_{s1\phi}$$

$$\text{Hence, } I_{R1\phi} = \left[\frac{V_{RM1\phi}}{Z_R} \right]$$

$$I_{m1\phi} = \left[\frac{V_{RM1\phi}}{Z_m} \right]$$